

Robotics
Autonomous systems
Machine control
Parallel DSP systems



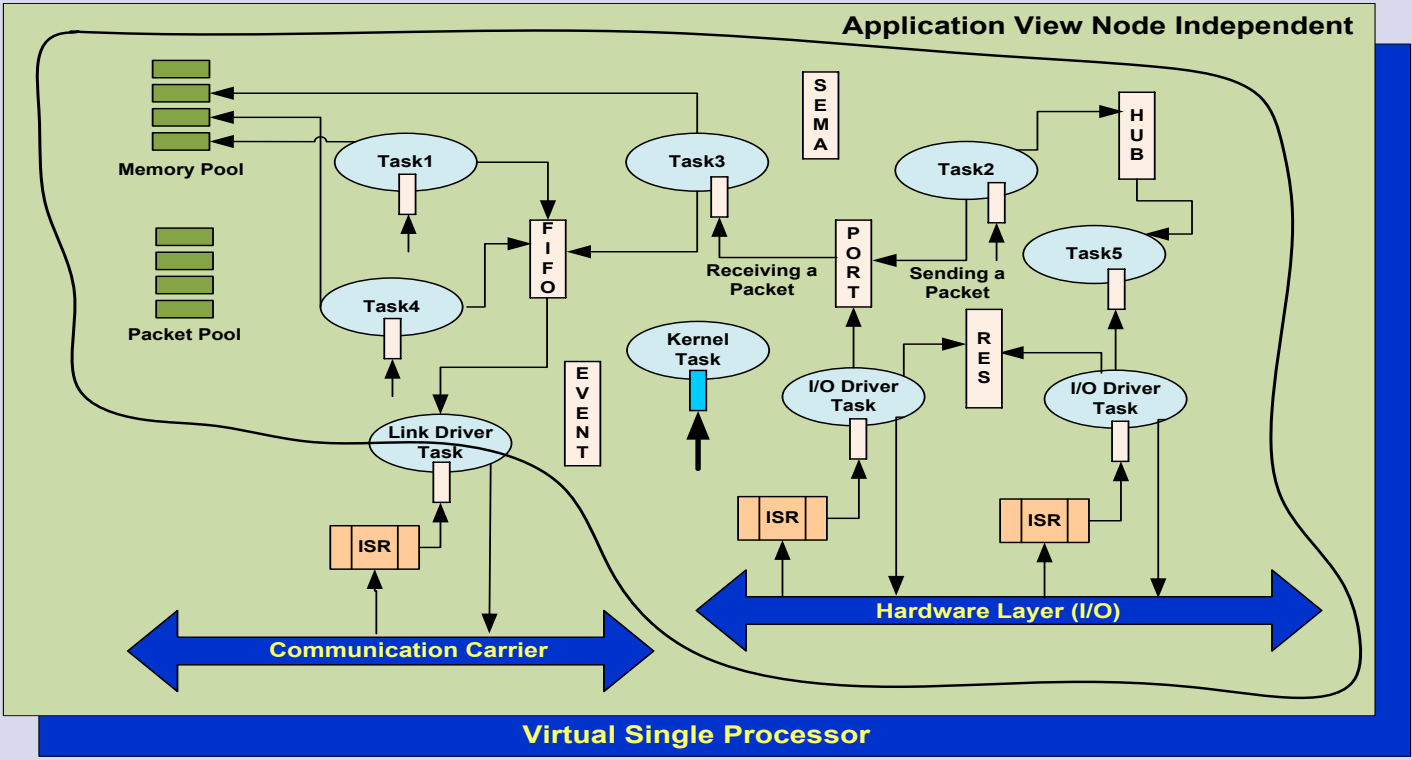
Many-core platforms
Fault Tolerant systems
Measuring and sensing
Safety critical systems

Ubiquitous computing with a unifying programming model

Concurrent Systems Composer

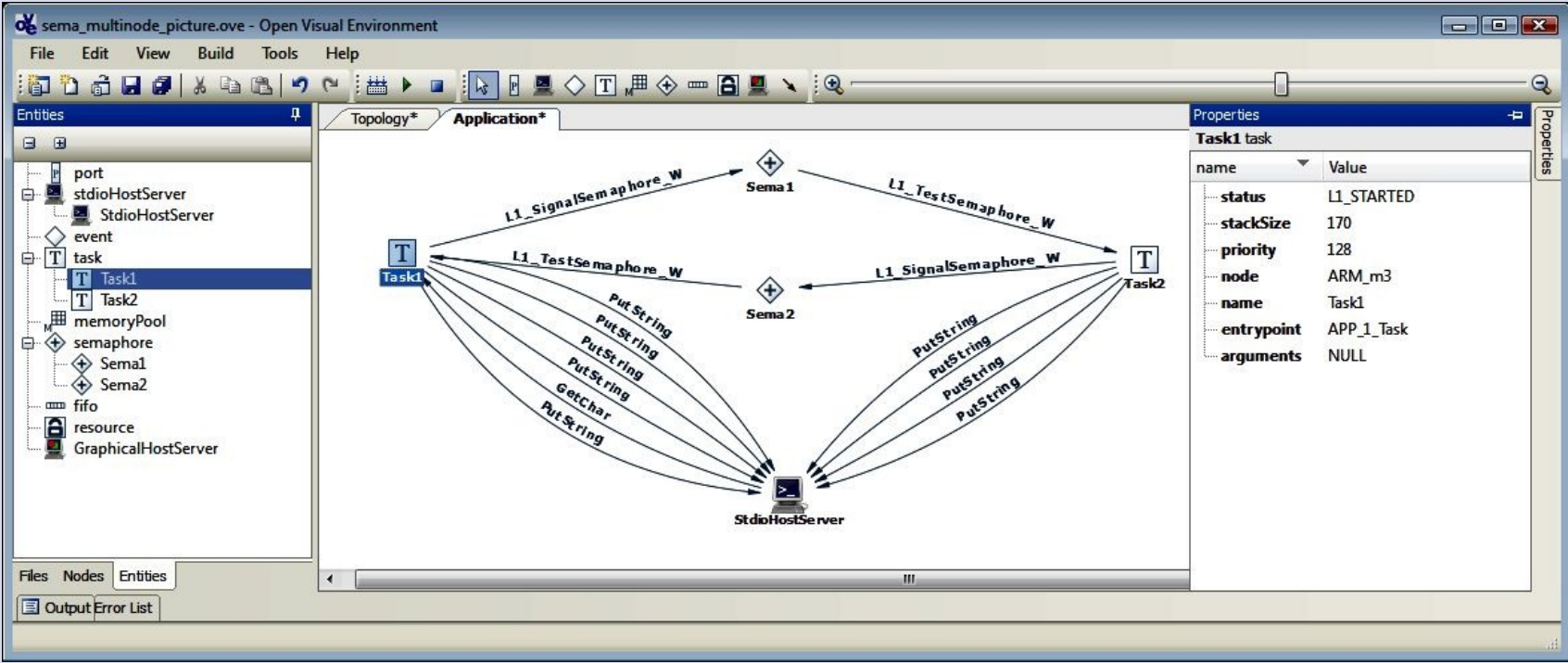
OPENVE ©

Formalized modeling
Simulation
code generation



OPENCOMRTOS ©

Formally developed
Network centric
5 to 10 Kbytes code size
Supports up to 64K nodes



Virtual Single Processor model

SAFEVIRTUALMACHINE
FOR C©

Dynamic and portable
binary C execution
(VM in 3.8 Kbytes)

OPENTRACER ©
Visual profiling of distributed
real-time applications

